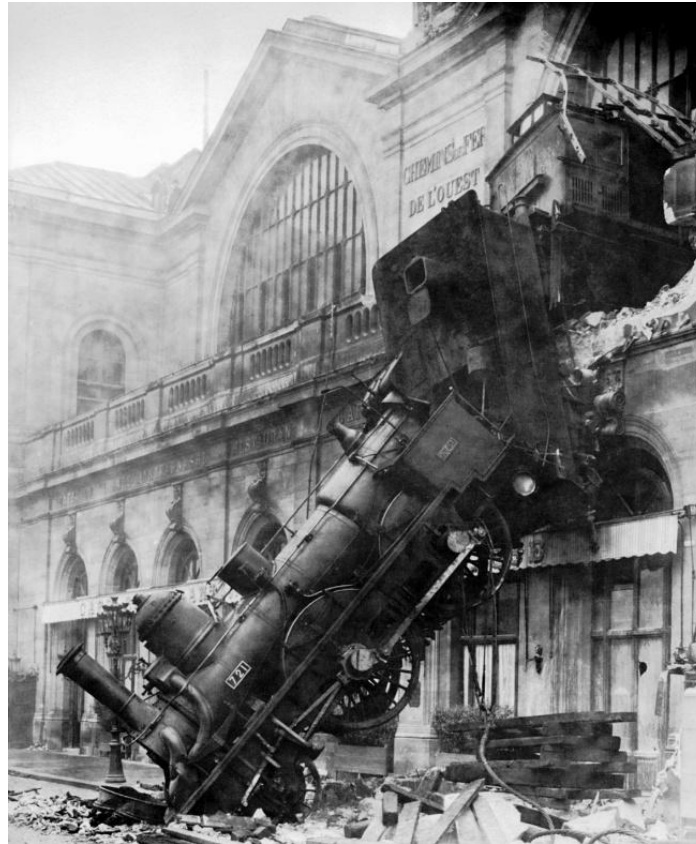


# Unit 2



**Estimation of parameters**

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# Summary

**1.- Bayes theorem**

**2.- Maximum likelihood method**

**3.- Estimation of reliability parameters from tests**

**4.- Confidence limits of parameters**

**5.- Accelerated life testing**

**6.- Determination of distribution models**

**7.- Empirical determination of survivor function**

**8.- Reliability growth**

**9.- Strength-stress models**

# BAYES THEOREM



From the “multiplication” of probability:

$$\text{prob}(A, B) = \text{prob}(A) \cdot \text{prob}(B | A)$$

$$\text{prob}(A, B) = \text{prob}(B) \cdot \text{prob}(A | B)$$

dividing the two equations we get:



## Bayes theorem

$$\text{prob}(A | B) = \frac{\text{prob}(B | A) \text{prob}(A)}{\text{prob}(B)}$$

That help us to reverse probabilities...

# Bayes theorem

$$\text{prob}(H | D) = \frac{\text{prob}(D | H) \text{prob}(H)}{\text{prob}(D)}$$

## Posterior prob(H | D):

What you want to know is the probability that your hypothesis is true given the data

## Likelihood (or L) prob(D | H):

What you know is your hypothesis. And therefore you can calculate the probability that your data “gathers” around your hypothesis

## Prior prob(H):

You might want to include any prior information about your hypothesis

## Evidence (E) prob(D):

Is “simply” a normalization factor...

# Bayes theorem



Likelihood  
Probability that our data  
describes the hypothesis

Prior  
Our forehand knowledge

$$P(H | D) = \frac{P(D | H) \cdot P(H)}{P(D)}$$

*T. Bayes.*

Posterior  
Probability that the hypothesis is true  
given the experimental data

Evidence  
Normalization factor

In our case is very simple...

# Bayes theorem



Likelihood  
Probability that our data  
describes the hypothesis

Maximum ignorance Prior

$$P(H | D) \propto \frac{P(D | H) \cdot P(H)}{P(D)}$$

Posterior  
Probability that the hypothesis is true  
given the experimental data

*T. Bayes.*

We only care about proportionality

Thus, assuming a maximum ignorance prior:

$$\mathit{prob}(H \mid D) \propto \mathit{prob}(D \mid H) = L$$

But what is exactly H, in practice?

It is a function and the parameters inside it

$$H_i(a, b) = a + bx_i$$



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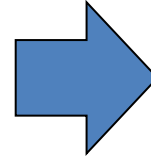
## Parameter estimation

We would like to estimate the best estimate of a quantity, given some data.

Let's define the posterior as:

$$\text{prob}(X | \{data\}) = P$$

The best estimate of X is given by a maximum in its probability and thus



$$\left. \frac{dP}{dX} \right|_{X_0} = 0$$

We want now to expand P as a Taylor series, since P varies too fast we take the logarithm of P

$$L = \ln(P) = \ln(\text{prob}(X | \{data\}))$$

The Taylor expansion of L is:

$$L = L(X_0) + \frac{1}{2} \left. \frac{d^2 L}{dX^2} \right|_{X_0} (X - X_0)^2 + \dots$$

Taking the first term we get for P:

$$\text{prob}(X | \{data\}) \approx A \exp \left[ \frac{1}{2} \left. \frac{d^2 L}{dX^2} \right|_{X_0} (X - X_0)^2 \right]$$

Let's compare with a gaussian

$$\text{prob}(X | \{data\}) \approx A \exp \left[ \frac{(X - X_0)^2}{2\sigma^2} \right]$$

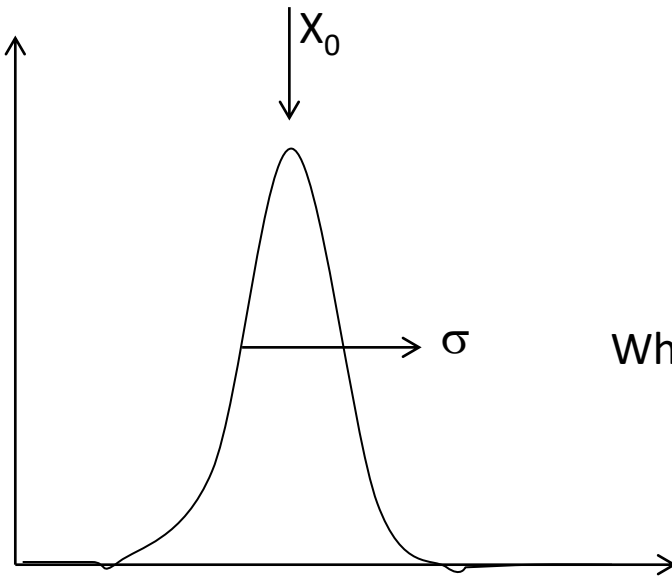
Taking the first term we get for P:

Comparing

$$\text{prob}(X | \{data\}) \approx A \exp \left[ \frac{1}{2} \frac{d^2 L}{dX^2} \Big|_{X_0} (X - X_0)^2 \right]$$

Let's compare with a gaussian

$$\text{prob}(X | \{data\}) \approx A \exp \left[ -\frac{(X - X_0)^2}{2\sigma^2} \right]$$



$$X = X_0 \pm \sigma$$

$$\sigma = \left( -\frac{d^2 L}{dX^2} \Big|_{X_0} \right)^{-1/2}$$

Where  $\frac{d^2 L}{dX^2} \Big|_{X_0}$  is always negative, so: no problem ;-)

Value plus error comes from a Taylor series

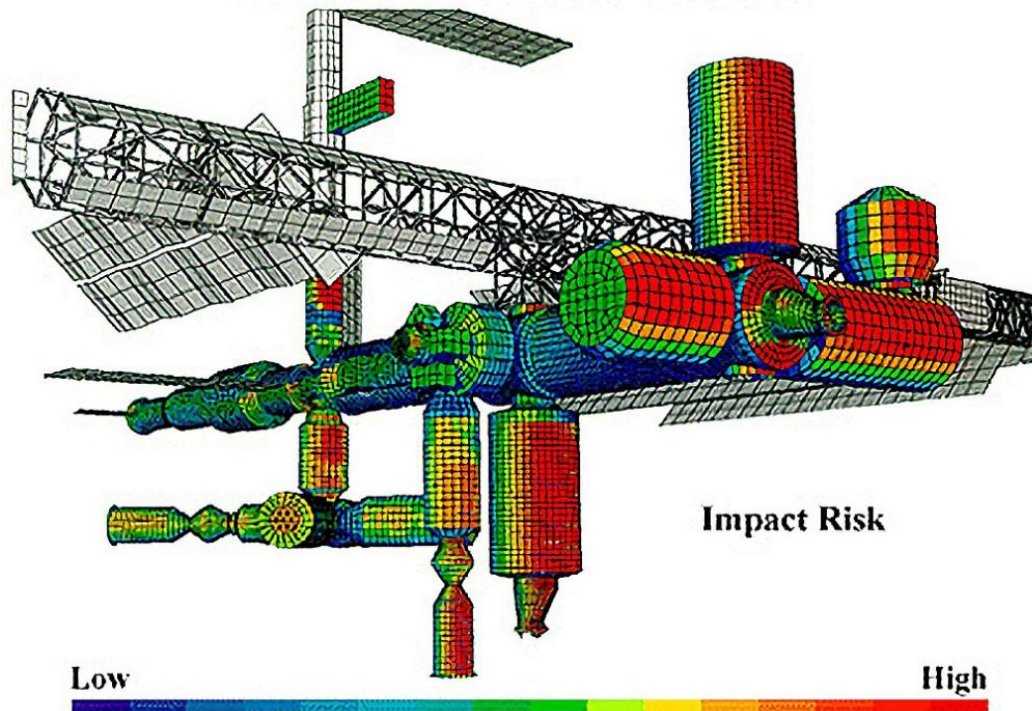
# Summary

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**Let's perform tests to quantify risk analysis...  
before sending the ISS to the space!!!!**

## **International Space Station**

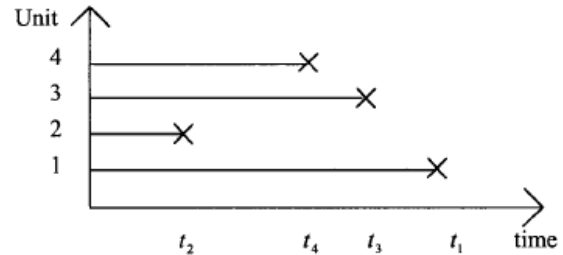
Probability of No Impacts From a > 1 cm Ø Debris



## Types of tests:

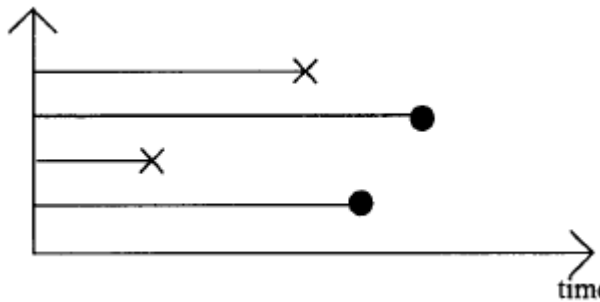
Let's assume that we perform a test on  $n=4$  components

### Complete data sets

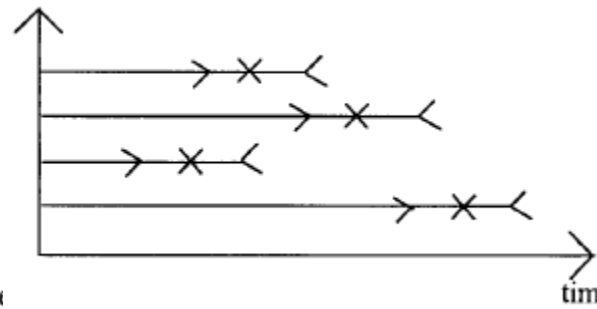


### Censored data sets

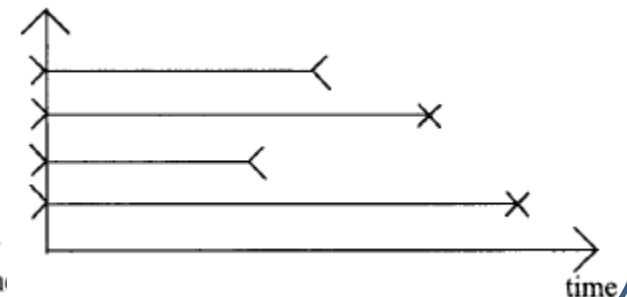
#### Right censored



#### Interval censored



#### Leftcensored

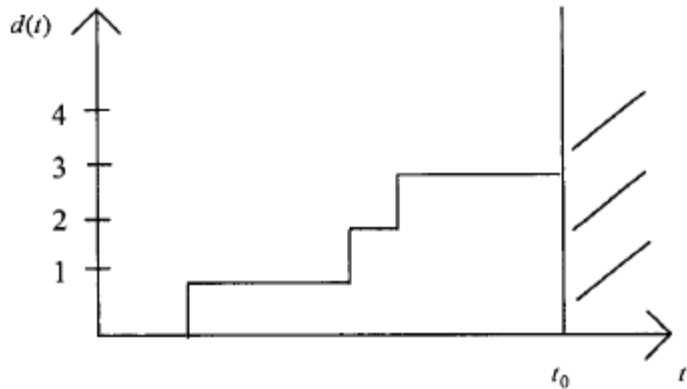


## Types of tests:

Test plans

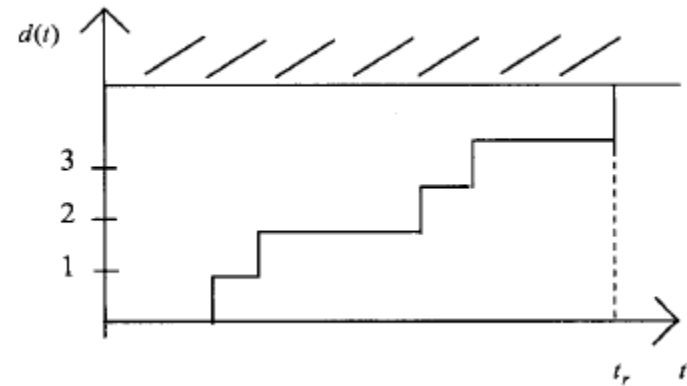
### **Type I**

Testing up to a given time  $t_0$

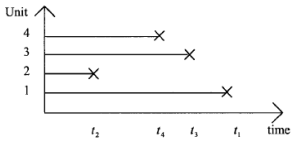


### **Type II**

Testing up to a given  $r$ -th failure



They can also be with (R) or without (W) replacement



Determine the failure ratio  $\lambda$ , or its inverse, the **Mean Time To Failure** MTTF  $\tau$  for  $n$  equal units in the case of **non-censored** data

We calculate the **likelihood** that

$$L = \prod_{i=1}^n \lambda e^{-\lambda t_i} = \lambda e^{-\lambda t_1} \cdot \lambda e^{-\lambda t_2} \cdot \lambda e^{-\lambda t_3} \dots \lambda e^{-\lambda t_n} = \lambda^n e^{-\lambda T} \leftarrow \boxed{T = \sum_{i=1}^n t_i}$$

we take the **logarithm**

$$\ln L = \ln \left( \lambda^n e^{-\lambda T} \right) = n \ln \lambda - \lambda T$$

we make the **derivative**

$$\frac{\partial \ln L}{\partial \lambda} = \ln \left( \lambda^n e^{-\lambda T} \right) = \frac{\partial (n \ln \lambda - \lambda T)}{\partial \lambda} = \frac{n}{\lambda} - T$$

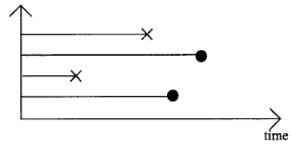
we **set it to zero** (find the maximum)

$$\frac{n}{\hat{\lambda}} - T = 0$$

we finally find the **most probable value** for  $\lambda$

$$\hat{\lambda} = \frac{n}{T}$$





Determine the failure ratio  $\lambda$ , or its inverse, the **Mean Time To Failure** MTTF  $\tau$  for  $n$  equal units in the case of **right-censored** data type I (until  $t_0$ )

We calculate the **likelihood** that

$$L = \prod_{i=1}^r \underbrace{f(t_i | \lambda)}_{\text{failure}} \prod_{i=r+1}^n \underbrace{R(t_0 | \lambda)}_{\text{time right-censored}} = \lambda^r e^{-\lambda \sum_{i=1}^r t_i} e^{-\lambda(n-r)t_0} = \lambda^r e^{-\lambda T} \quad \leftarrow \quad T = \sum_{i=1}^n t_i + (n-r)t_0$$

we take the **logarithm**

$$\ln L = \ln(\lambda^r e^{-\lambda T}) = r \ln \lambda - \lambda T$$

we make the **derivative**

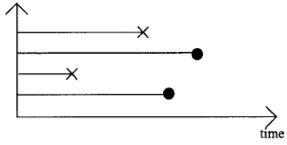
$$\frac{\partial \ln L}{\partial \lambda} = \ln(\lambda^r e^{-\lambda T}) = \frac{\partial (r \ln \lambda - \lambda T)}{\partial \lambda} = \frac{r}{\lambda} - T$$

we **set it to zero** (find the maximum)

$$\frac{r}{\hat{\lambda}} - T = 0$$

we finally find the **most probable value** for  $\lambda$

$$\hat{\lambda} = \frac{r}{T}$$



Determine the failure ratio  $\lambda$ , or its inverse, the **Mean Time To Failure** MTTF  $\tau$  for  $n$  equal units in the case of **right-censored** data type II (until  $r$  units fail)

We calculate the **likelihood** that

$$L = \prod_{i=1}^r \underbrace{f(t_i | \lambda)}_{\text{failure}} \prod_{i=r+1}^n \underbrace{R(t_i | \lambda)}_{\text{right-censored}} = \lambda^r e^{-\lambda \sum_{i=1}^r t_i} e^{-\lambda \sum_{i=r+1}^n t_i} = \lambda^r e^{-\lambda T} \quad \leftarrow \quad T = \sum_{i=1}^n t_i + (n-r)t_r$$

we take the **logarithm**

$$\ln L = \ln(\lambda^r e^{-\lambda T}) = r \ln \lambda - \lambda T$$

we make the **derivative**

$$\frac{\partial \ln L}{\partial \lambda} = \ln(\lambda^r e^{-\lambda T}) = \frac{\partial (r \ln \lambda - \lambda T)}{\partial \lambda} = \frac{r}{\lambda} - T$$

we **set it to zero** (find the maximum)

$$\frac{r}{\hat{\lambda}} - T = 0$$

we finally find the **most probable value** for  $\lambda$

$$\hat{\lambda} = \frac{r}{T}$$

...BUT YOU DO NOT WANT TO STOP PRODUCTION until  $r$  components fail

Determine the failure ratio  $\lambda$ , or its inverse, the **Mean Time To Failure** MTTF  $\tau$  for  $n$  equal units in the case of **right-censored** data type I (until  $t_0$ )

WITH REPLACEMENT

Let's do it for a single component  $n=1$  that is replaced each time it fails

$n=1$

$$L = \lambda e^{-\lambda t_1} \lambda e^{-\lambda(t_2-t_1)} \lambda e^{-\lambda(t_3-t_2)} \dots \lambda e^{-\lambda(t_0-t_r)} = \lambda^r e^{-\lambda t_0}$$



... for  $n$  components

$$L = \lambda^r e^{-\lambda n t_0} = \lambda^r e^{-\lambda T} \quad \leftarrow \boxed{T = n t_0}$$

$n>1$

doing the same calculations as before...

we finally find the **most probable value** for  $\lambda$

$$\hat{\lambda} = \frac{r}{T}$$

...BUT YOU DO NOT WANT TO STOP PRODUCTION until  $r$  components fail

Determine the failure ratio  $\lambda$ , or its inverse, the **Mean Time To Failure** MTTF  $\tau$  for  $n$  equal units in the case of **right-censored** data type II (until  $r$ -th failure)

WITH REPLACEMENT

Let's do it for a single component  $n=1$  that is replaced each time it fails

$n=1$

$$L = \lambda e^{-\lambda t_1} \lambda e^{-\lambda(t_2-t_1)} \lambda e^{-\lambda(t_3-t_2)} \dots \lambda e^{-\lambda(t_0-t_r)} = \lambda^r e^{-\lambda t_0}$$



... for  $n$  components

$$L = \lambda^r e^{-\lambda n t_0} = \lambda^r e^{-\lambda T} \quad \leftarrow \boxed{T = n t_r}$$

$n>1$

doing the same calculations as before...

we finally find the **most probable value** for  $\lambda$

$$\hat{\lambda} = \frac{r}{T}$$

summarizing: We want to keep the notation  $\hat{\lambda} = \frac{r}{T}$

so, we change the meaning of T...

not censored, no replacement  $T = \sum_{i=1}^n t_i$

	Censored Type I (unit $t_0$ )	Censored Type II (unit $r$ -th failure)
Without replacement	$T = \sum_{i=1}^n t_i + (n-r)t_0$	$T = \sum_{i=1}^n t_i + (n-r)t_r$
With replacement	$T = nt_0$	$T = nt_r$

